libcppa Type-safe Messaging Systems in C++

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Hochschule für Angewandte Wissenschaften Hamburg Hamburg University of Applied Sciences



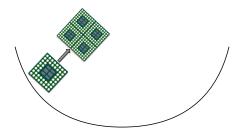
Agenda

1 Introduction

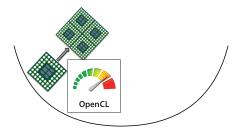
- Challenges of Scalable Software
- What the Standard Provides
- 2 The Actor Model & libcppa
 - Benefits
 - Actors in C++11
 - API & Examples
- 3 Actors vs Threads
- 4 Performance Evaluation
 - Overhead of Actor Creation
 - Performance of N:1 Communication
 - Performance in a Mixed Scenario
 - Scaling Behavior of Message Passing
- 5 Conclusion

Developers face not one, but multiple trends:

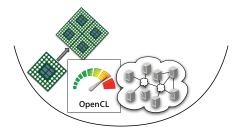
More cores on both desktop & mobile plattforms



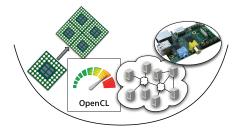
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- SIMD components: GPUs can vastly outperform CPUs



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- Embedded HW & "The Internet of Things"



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- Cloud computing: "Infrastructure as a service"
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- Embedded HW & "The Internet of Things"
- \Rightarrow Heterogeneous platforms, concurrency & distribution



Raising the Level of Abstraction

Threads, Locks and Futures as found in the STL are **not** a sufficient abstraction. We should be enabled to ...

- Easily split application logic into as many tasks as needed
- Avoid race conditions by design (no locks!)
- Compose large systems out of small components *easily*
- Keep interfaces between software components stable:
 - Whether or not they run on the same host
 - Whether or not they run on specialized hardware
 - \Rightarrow Flexible composition

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All of these criteria are met by the actor model.

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 - Divide workload by spawning actors
 - Network-transparent messaging
- Provides strong failure semantics
 - Hierarchical error management
 - Re-deployment at runtime

Actors and Native Programming

Actors have not yet entered the native programming domain

- Need to broaden range of applications
- Deploy actors in performance-critical systems

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- Need to broaden range of applications
- Deploy actors in performance-critical systems
- Actor systems need to include heterogeneous hardware
 - Integration of specialized HW components (GPGPU)
- Actor systems not available for embedded systems
 - Why not model the "Internet of Things" as network of actors?
 - HW platform should not dictate programming model
 - Portability & code re-use for developing IoT applications

Actors in C++11

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- Uses internal DSL for pattern matching of messages

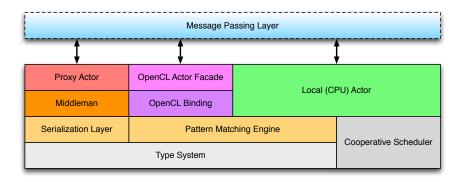
Type System

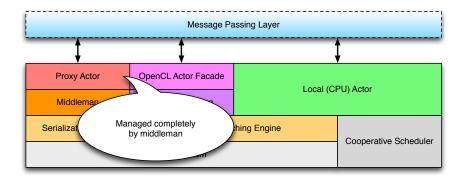
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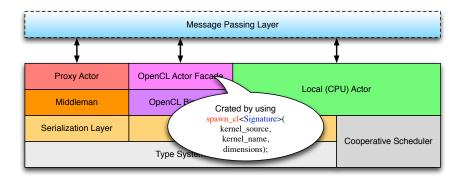
Serialization Layer	Pattern Matching Engine			
Type System				

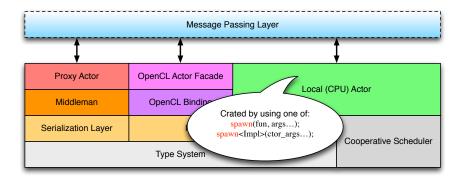
Middleman	OpenCL Binding		
Serialization Layer	Pattern Matching Engine		Cooperative Schoduler
Type System			Cooperative Scheduler

Proxy Actor	OpenCL Actor Facade	Local (CPU) Actor	
Middleman	OpenCL Binding		
Serialization Layer	Pattern Matching Engine		Cooperative Schoduler
Type System			Cooperative Scheduler









API – Creating Actors

actor spawn(Ts&&... args);

- Create actors from either functors or classes
- Spawn options can be used for monitoring, detaching, etc.
- Creates event-based actors per default

API – Event-based Actor Class

```
class event_based_actor : ... {
```

```
template<typename... Ts>
void send(actor whom, Ts&&... what);
```

```
template<typename... Ts>
response_handle sync_send(actor whom, Ts&&... what);
```

```
void become(behavior bhvr);
```

```
void quit(uint32_t reason);
```

// ...

};

- Base for class-based actors
- Type of implicit self pointer for functor-based actors

API – Remote Communication

// makes actor accessible via network
void publish(actor whom, uint16_t port);

// get handle to remotely running actor actor remote_actor(std::string host, uint16_t port);

- Message passing is network transparent
- Both local and remote actors use handles of type actor
- Network primitives not exposed to programmer

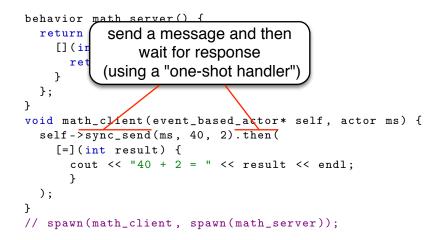
Example

```
behavior math_server() {
  return {
    [](int a, int b) {
      return a + b;
    }
 };
}
void math_client(event_based_actor* self, actor ms) {
  self->sync_send(ms, 40, 2).then(
    [=](int result) {
      cout << "40 + 2 = " << result << endl;
      }
  );
}
   spawn(math_client, spawn(math_server));
```

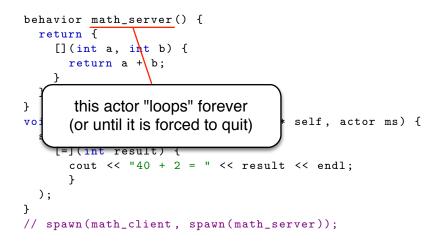
Example



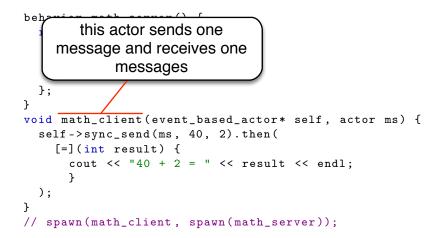
Example



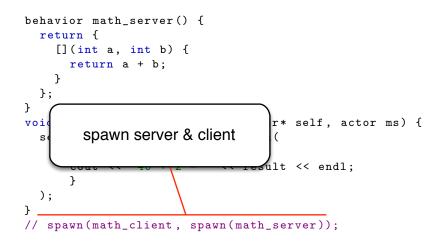
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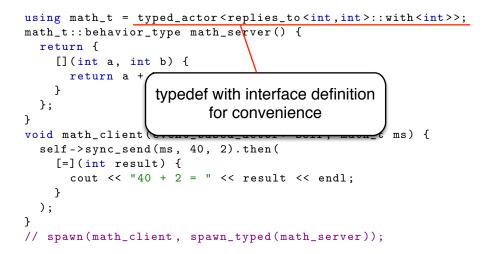
API – Type Safety

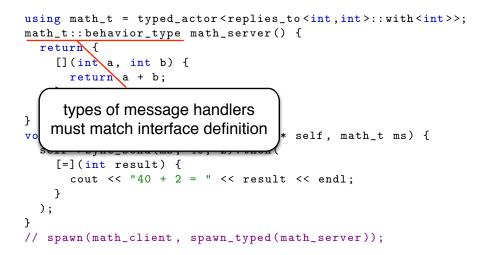
- All functions are available as typed version
- Strongly typed actors use handles of type typed_actor<...>
- Interface is defined using replies_to<...>::with<...> notation
- Messaging to/from typed actors fully checked at compile time

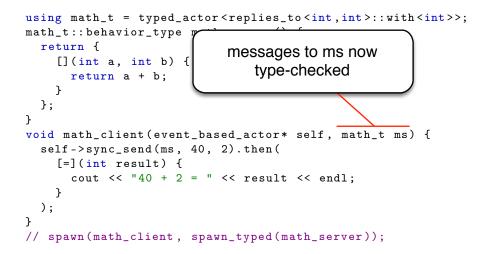
API – Typed Actor Handles

Typed actor handles can be assigned to subtypes (even remote!):

```
using math_t = typed_actor<replies_to<int,int>::with<int>>;
math_t::behavior_type math_server() {
  return {
    [](int a, int b) {
      return a + b:
 };
}
void math_client(event_based_actor* self, math_t ms) {
  self->sync_send(ms, 40, 2).then(
    [=](int result) {
      cout << "40 + 2 = " << result << endl:
    }
  );
}
// spawn(math_client, spawn_typed(math_server));
```







API – Monitoring Example

```
behavior worker(); // sometimes fails
behavior master(event_based_actor* self) {
  auto w = self->spawn<monitored>(worker);
  return {
    [=](int a, int b) {
      self->send(w, a, b);
    },
    [=](const down_msg& msg) {
      if (msg.source == w) {
        // start a new worker
        self->become(master(self));
      }
  };
}
```

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Actors vs Threads

Matrix multiplication as scaling behavior showcase:

- Large number of independent tasks
- Can make use of C++11's async
- Simple to port algorithm to GPU (because: why not?)

Multiply Matrices – Matrix Class

```
static constexpr size_t matrix_size = /*...*/;
```

```
// always rows == columns == matrix_size
class matrix {
  public:
    float& operator()(size_t row, size_t column);
    const vector<float>& data() const;
    // ...
  private:
    vector<float> m_data; // glorified vector
};
```

Multiply Matrices – Simple Loop

Multiply Matrices – std::async

```
matrix async_multiply(const matrix& lhs,
                       const matrix& rhs) {
  matrix result;
  vector < future < void >> futures:
  futures.reserve(matrix_size * matrix_size);
  for (size_t r = 0; r < matrix_size; ++r) {</pre>
    for (size_t c = 0; c < matrix_size; ++c) {</pre>
      futures.push_back(async(launch::async, [&,r,c] {
        result(r, c) = dot_product(lhs, rhs, r, c);
      })):
    }
  }
  for (auto& f : futures) f.wait();
  return move(result);
}
```

Multiply Matrices – libcppa Actors

```
matrix actor_multiply(const matrix& lhs,
                        const matrix& rhs) {
  matrix result;
  for (size_t r = 0; r < matrix_size; ++r) {</pre>
    for (size_t c = 0; c < matrix_size; ++c) {</pre>
      spawn([&,r,c] {
        result(r, c) = dot_product(lhs, rhs, r, c);
      });
    }
  }
  await_all_actors_done();
  return move(result);
}
```

Multiply Matrices – OpenCL Actors

```
static constexpr const char* source = R"__(
  __kernel void multiply(__global float* lhs,
                         __global float* rhs,
                         __global float* result) {
    size_t size = get_global_size(0);
    size_t r = get_global_id(0);
    size_t c = get_global_id(1);
    float dot_product = 0;
    for (size_t k = 0; k < size; ++k)
      dot_product += lhs[k+c*size] * rhs[r+k*size];
    result[r+c*size] = dot_product;
 }
)__";
```

Multiply Matrices – OpenCL Actors

```
matrix opencl_multiply(const matrix& lhs,
                       const matrix& rhs) {
  using fvec = vector <float >;
  using cfvec = const fvec&;
                      // function signature
  auto worker = spawn_cl<fvec (cfvec, cfvec)>(
                  // code, kernel name & dimensions
                  source, "multiply",
                  {matrix_size, matrix_size});
  scoped_actor self;
  self->send(worker, lhs.data(), rhs.data());
  matrix result:
  self->receive([&](fvec& res vec) {
    result = move(res_vec);
 });
  return move(result);
}
```

Setup: 12 cores, Linux, GCC 4.8, 1000x1000 matrices

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time ./simple_multiply
Om9.029s
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time ./async_multiply
terminate called after throwing an instance of 'std::system_error'
what(): Resource temporarily unavailable

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... apparently, std::async is syntactic sugar for starting threads ... and one cannot start 1,000,000 threads

Multiply Matrices – Summary

- Threads do not scale up to large numbers, actors do
- Spawning actors is fast
 - A million actors in $\leq 1.1 \, s$
 - Approach ideal speedup despite spawning >80k actors per CPU
- Yes, porting algorithms to GPUs is indeed worthwhile
 - Speedup is ludicrous
 - Shouldn't surprise anybody

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Benchmarks are based on the following implementations:

libcppa C++ (GCC 4.8.1) with libcppa
scala Scala 2.10 with the Akka library
erlang Erlang 5.10.2

System setup:

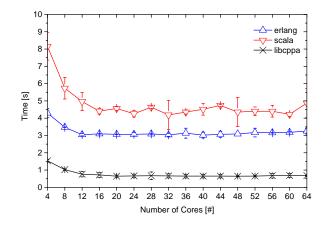
- Four 16-core AMD Opteron 2299 MHz
- JVM configured with a maximum of 10 GB of RAM
- We vary the number of CPU cores from 4 to 64

Overhead of Actor Creation

- Fork/join workflow to compute 2^N
 - Each fork step spawns two new actors
 - Join step sums up messages from children
 - Each actor at the leaf sends 1 to parent

Benchmark creates \approx 1,000,000 actors (N = 20)

Overhead of Actor Creation



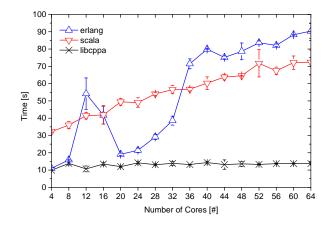
All three implementations scale up to large actor systems
libcppa performs best: 1M actors in < 1s for 8 or more cores

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Performance of 1:N Communication

- 100 senders transmitting 100k messages each to a single receiver
- Stresses performance of receive for central actors
- More HW concurrency adds more collisions on receiver mailbox

Performance of N:1 Communication



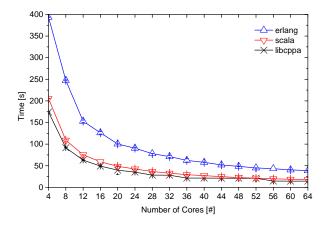
Runtime increases significantly for Erlang and Scala
 libcppa remains almost constant

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Performance in a Mixed Scenario

- Mixed operations under work load
- 100 rings of 50 actors each
- Token-forwarding on each ring until 1k iterations are reached
- 5 re-creations per ring
- One prime factorization per (re)-created ring to add work load
- Doubling the number of cores should (nearly) halve the runtime

Performance in a Mixed Scenario



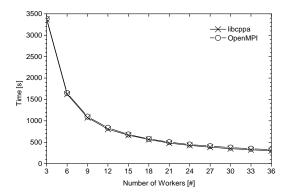
 \blacksquare Tail-recursive prime factorization in Scala as fast as in C++ \blacksquare libcppa on 64 cores still $\approx 20\,\%$ faster

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Scaling Behavior of Message Passing

- Calculate images of the Mandelbrot set in C++
- Distributed using (1) libcppa and (2) OpenMPI
 - Same source code for calculation
 - Only the message passing layers differ

Scaling Behavior of Message Passing



- Both implementations exhibit equal scaling behavior
- Doubling the number of worker nodes halves the runtime
- libcppa 20-30 s faster, despite higher level of abstraction

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- Native C++ actor system
 - Pattern Matching for messages as internal DSL
 - High level of abstraction without sacrificing performance
- Currently ported to RIOT-os¹ for embedded HW support

¹http://www.riot-os.org/

libcppa Facts Sheet

- Open source (GPLv2) C++11 actor library
- Runs on GCC \geq 4.7, Clang \geq 3.2 (Linux + Mac)
- Will run on MSVC once it is C++11 complete (runs on MinGW)
- Hosted on GitHub
- Feedback & contributions always welcome!
- Hot topics in the iNET group:
 - Actors on ARM / embedded systems
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- Currently in (preliminary) submission process to Boost!

Thank you for your attention!

Developer blog: http://libcppa.org

Sources: https://github.com/Neverlord/libcppa

iNET working group: http://inet.cpt.haw-hamburg.de